

Performance Analysis of Time-Triggered Ether-Networks Using Off-The-Shelf-Components

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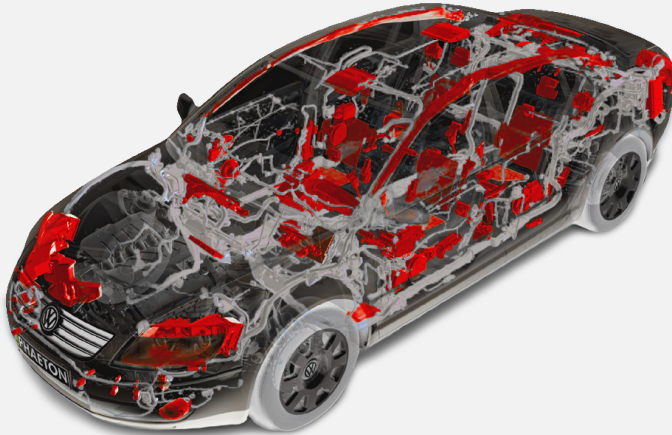
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Real-time Ethernet in automotive applications:

- In-vehicle networks are very complex
- New automotive applications require more bandwidth
- Real-time Ethernet is widely deployed in backbones of industrial plants
- Comparable real-time characteristics in vehicles

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Low cost performance analysis with time-triggered packet generation:

- Missing performance analyzer instruments in tool chain
- Tools for standard switched Ethernet are not suitable
- Flexible embedded pc based tools gain importance

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Distinction between software and hardware based measurements

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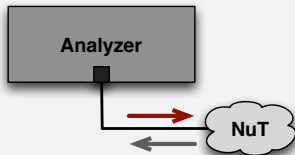
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Distinction between software and hardware based measurements

- Collection on one network port only



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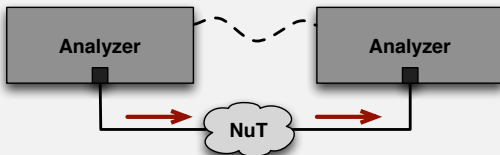
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Distinction between software and hardware based measurements

- Collection on one network port only
- Distributed measurement with synchronized timebase



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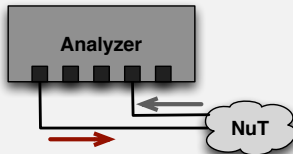
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Distinction between software and hardware based measurements

- Collection on one network port only
- Distributed measurement with synchronized timebase
- One physical clock and several network ports



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3 strategies to enable real-time characteristics on Ethernet-based networks

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3 strategies to enable real-time characteristics on Ethernet-based networks

- Token-based systems
 - Used in Ethercat in process automation

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3 strategies to enable real-time characteristics on Ethernet-based networks

- Token-based systems
 - Used in Ethercat in process automation
- Bandwidth limiting systems
 - For instance AFDX in Airplanes (A380 and Boeing 787)

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3 strategies to enable real-time characteristics on Ethernet-based networks

- Token-based systems
 - Used in Ethercat in process automation
- Bandwidth limiting systems
 - For instance AFDX in Airplanes (A380 and Boeing 787)
- Time-triggered systems
 - Automotive industry (FlexRay) and process automation (Profinet)

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3 Traffic Classes in TTEthernet

1 Time-Triggered

- Highest priority and used for hard real-time data
- Strictest requirements in transmission

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3 Traffic Classes in TTEthernet

1 Time-Triggered

- Highest priority and used for hard real-time data
- Strictest requirements in transmission

2 Rate-Constrained

- Also suitable for real-time communication
- Complies to the AFDX protocol

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3 Best-Effort

- Standard Ethernet traffic
- No guarantee in transmission

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- Also suitable for real-time communication
- Complies to the AFDX protocol

3 Best-Effort

- Standard Ethernet traffic
 - No guarantee in transmission
-
- Time synchronization for a global time base
 - Works transparent to the Ethernet-Protocol-Layer

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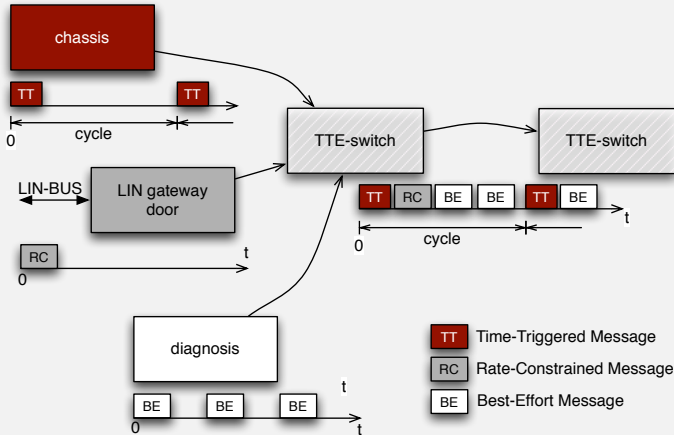
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Available OS tools:

- Tools running in Userspace (e.g. ping, traceroute)
- Precision in milliseconds provided by OS
- Scheduling and hardware-layer produce overhead
- OS tools measure round-trip-time

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Our approach:

- Measurement on a low-level base → Kernel-space in Linux
- RT-Linux utilization for enhanced interrupt handling
- Exact timing behavior by using special functions

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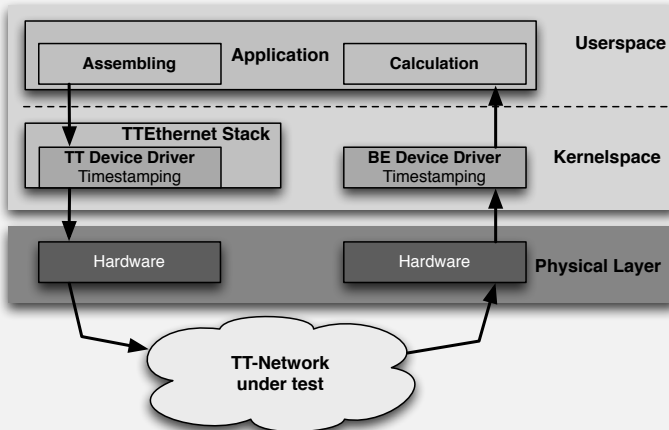
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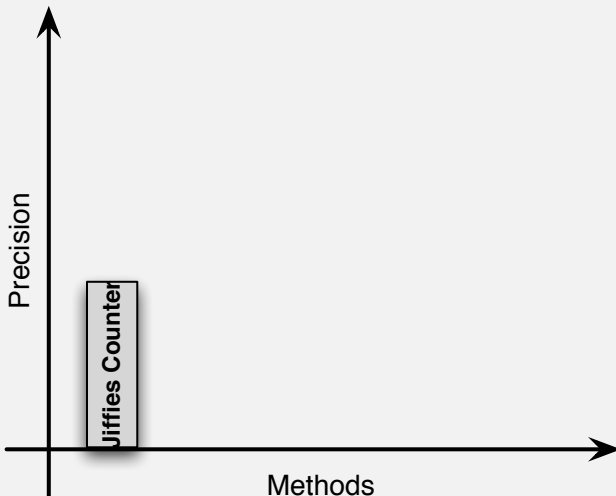
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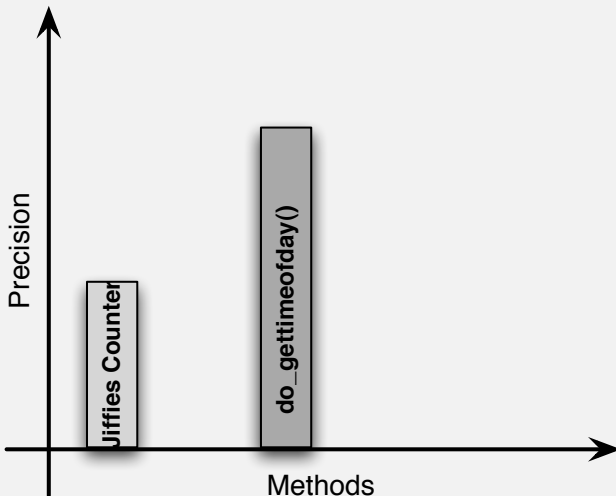
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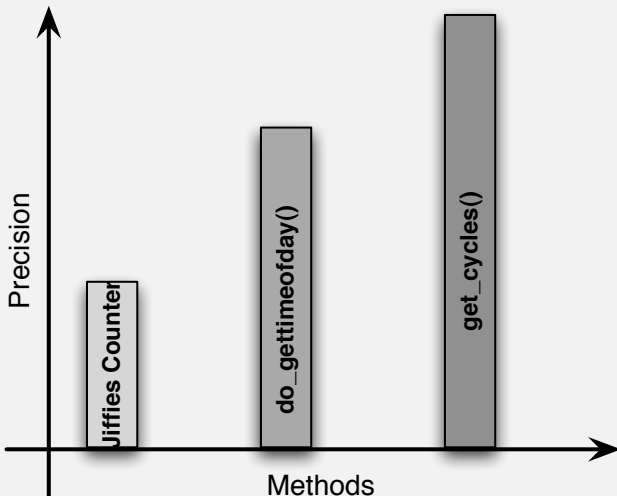
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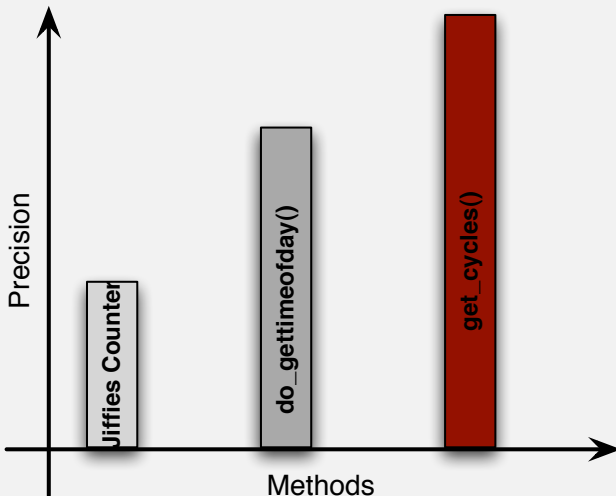
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2 approaches to get timing information of a single frame

- 1 Storing information in Kernel space
 - High implementation cost (limited Kernel functions)
 - Additional information has to be stored

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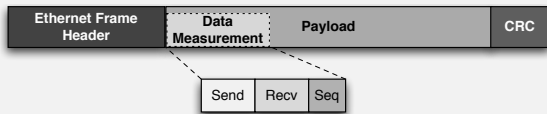
2 approaches to get timing information of a single frame

1 Storing information in Kernel space

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- Additional information has to be stored

2 Modifying Ethernet frames with timestamps

- A lightweight approach
- Assigning timestamps to frames in an easy way
- Measurement can be done promptly without reading and storing information



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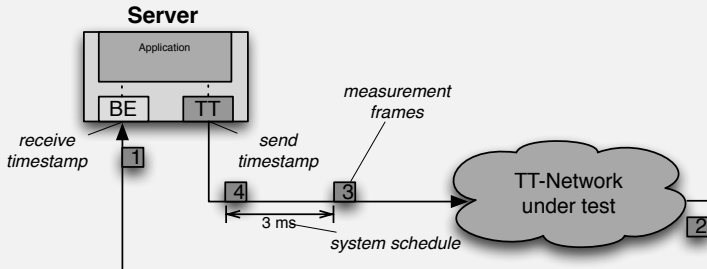
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- 3ms System Schedule for each TT-Frame
- 350 μ s static switch delay



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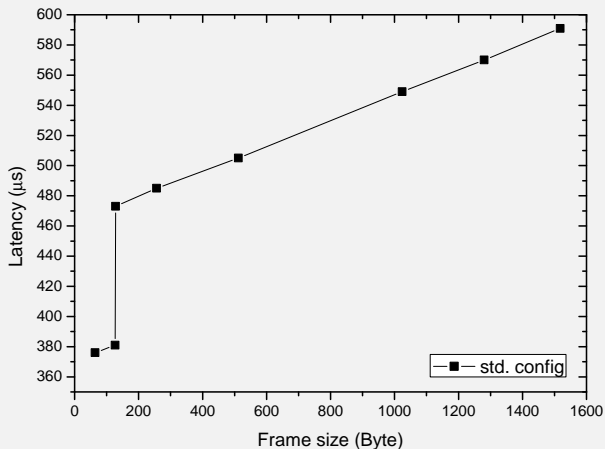
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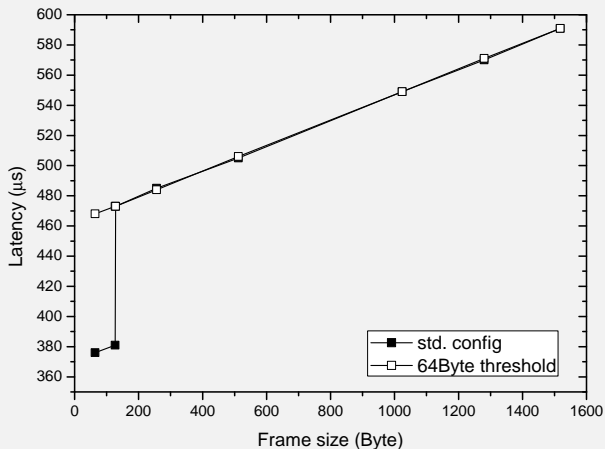
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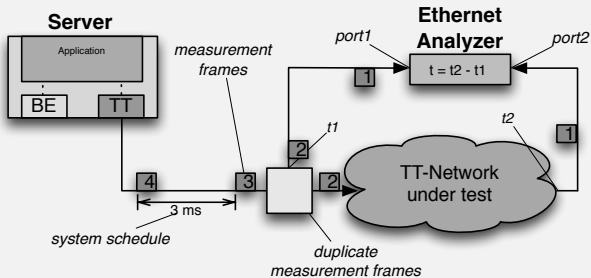
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- Observation: A specific hardware and driver delay has to be subtracted for each measurement

1 High precision Ethernet analyzer tool



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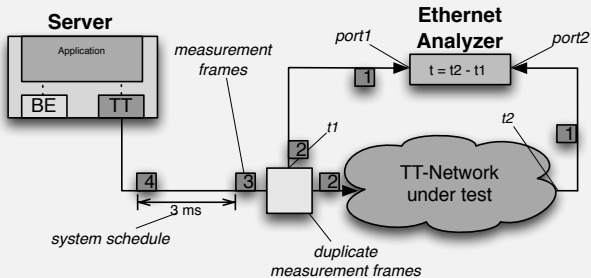
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1 High precision Ethernet analyzer tool



2 Mathematical framework

- Analytical method to calculate latency, bandwidth and jitter

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	measurement approach	hardware sniffing	mathematical model
min. framelength	$355\mu s$	$364\mu s$	$355.125\mu s$
max. framelength	$471\mu s$	$479\mu s$	$471.445\mu s$

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	measurement approach	hardware sniffing	mathematical model
min. framelength	$355\mu s$	$364\mu s$	$355.125\mu s$
max. framelength	$471\mu s$	$479\mu s$	$471.445\mu s$

Difference of $9\mu s$ is due to the used duplication switch

	measurement approach	hardware sniffing	mathematical model
min. framelength	$355\mu s$	$355\mu s$	$355.125\mu s$
max. framelength	$471\mu s$	$470\mu s$	$471.445\mu s$

Measurements

Latency Comparison COTS switch and TTEthernet Switch



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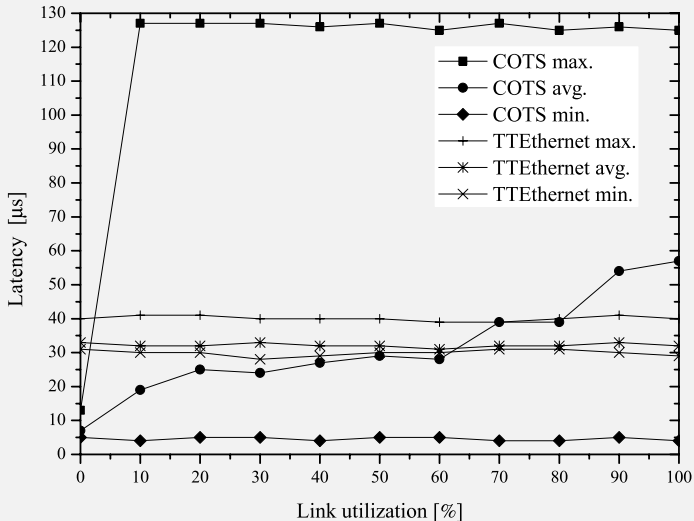
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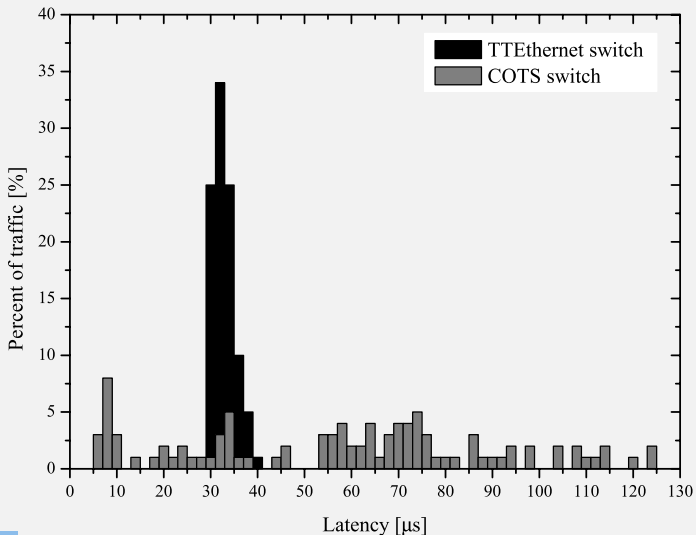
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Latency Distribution Graph



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Conclusion:

- Performance analysis with COTS in single-digit microseconds precision
- Synchronized packet generation
- Utilization of RT-Linux, modified device drivers and TTEthernetstack

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Outlook:

- Validation using hardware with specifically low receive and copy delay
- Adjustment of this approach on an ARM-based micro controller to increase resolution

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Thank you!

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Thank you for your attention!

- Website of research group:
<http://www.informatik.haw-hamburg.de/core.html>

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